

<http://www.mapleprimes.com/questions/143775-How-To-Find-The-Integral>

```
> restart; interface(version);
Classic Worksheet Interface, Maple 16.02, Windows, Nov 18 2012, Build ID 788210
```

Task

```
> sinc:= t -> sin(t)/t; # non-normalized sinc
#Sinc:= t -> 1/t/Pi*sin(t*Pi); # normalized sinc
a:= k -> 2^(-k);
#sinc(x*a(k))': '%'= combine(%);

sinc := t →  $\frac{\sin(t)}{t}$ 
a := k →  $2^{(-k)}$ 

> `Assertion: `;
Pi = 'Int(Product(sinc(x*a(k)), k = 0 .. n), x = -infinity .. infinity)',
n in IN[0];

Assertion:


$$\pi = \int_{-\infty}^{\infty} \prod_{k=0}^n \text{sinc}(x a(k)) dx, n \in \mathbb{N}_0$$


> `some first check: `;
N:='N':
'Int(Product(sinc(x*a(k)), k = 0 .. n), x = -infinity .. infinity)':
combine(%):
['seq'( eval(% , n=N), N = 0 .. 6)];
`'=value(%); N:='N':

some first check:


$$\left[ \text{seq} \left( \int_{-\infty}^{\infty} \prod_{k=0}^N \frac{\sin(x 2^{(-k)}) 2^k}{x} dx, N = 0 .. 6 \right) \right]$$


= [π, π, π, π, π, π, π]

> assume(k::nonnegint); getassumptions(k);
{k::AndProp(integer, RealRange(0, ∞))}
```

Idea: use Fourier methods, as in Borwein, David; Borwein, Jonathan M. (2001), "Some remarkable properties of sinc and related integrals", The Ramanujan Journal 5 (1): 73–89, Thm 2 (ii) at <http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.40.8186> (for a download to avoid those expensive commercial downloads).

>

Recall Fourier transformation

```
> with(inttrans);
NumericEventHandler(invalid_operation =
'Heaviside/EventHandler'(value_at_zero = 1)):
'Heaviside(0)': '%'=%;

[addtable, fourier, fouriercos, fouriersin, hankel, hilbert, invfourier, invhilbert, invlaplace, invmellin, laplace,
mellin, savetable]

Heaviside(0) = 1
```

```
> # notation
Phi = 'Fourier transform', (Phi@@(-1)) = 'inverse Fourier transform';
`';
"non-unitary convention";
fourier( f(x),x,t): '%'= convert(% , Int);

Phi = Fourier transform, Phi(-1) = inverse Fourier transform

"non-unitary convention"

fourier(f(x), x, t) =  $\int_{-\infty}^{\infty} f(x) e^{(-I x t)} dx$ 

> Phi^2 = -2*Pi*id;
'fourier(fourier(f(x),x,t),t,x) = 2*Pi*f(-x)'; is(%);
#'fourier(f(t),t,x) = 2*Pi*invfourier(f(t),t,-x)';
#convert(% , Int): is(%);

Phi2 = -2 π id
fourier(fourier(f(x), x, t), t, x) = 2 π f(-x)
true
```

Rectangles and sinc

Rectangles and sinc functions are Fourier transform pairs

```
> piecewise(a <= t and t <= b, 1, 0):
rect:= unapply(% , a,b, t);
`=rect(a,b, t),
assuming a < b !!`;

rect := (a, b, t) → piecewise(a ≤ t and t ≤ b, 1, 0)
= {  $\begin{matrix} 1 & a \leq t \text{ and } t \leq b \\ 0 & \text{otherwise} \end{matrix}$  , assuming a < b !!

> 'sinc(x)' = 'fourier(rect(-1,1,z), z,x)'/2; is(%);

sinc(x) =  $\frac{1}{2}$  fourier(rect(-1, 1, z), z, x)

true

> s:= (k,z) -> 2^(-1+k)*rect(-2^(-k), 2^(-k), z);
`';
'sinc(x*a(k))' = fourier('s'(k,z), z,x); is(%);

s := (k, z) →  $2^{(k-1)} \text{rect}(-2^{(-k)}, 2^{(-k)}, z)$ 

sinc(x a(k)) = fourier(s(k, z), z, x)
true
```

>

Convolution

```
> # take some care for variables if using the following in a simple way ...

Conv:=(f,g)-> tau -> Int(f(tau-y)*g(y), y = -infinity .. infinity);
#Conv(f,g);

Conv := (f, g) →  $\tau \rightarrow \int_{-\infty}^{\infty} f(\tau - y) g(y) dy$ 
```

That gives a commutative algebra structure with multiplication = convolution. Or in a less educated language: one can manipulate like usual multiplication (a unity is missing)

Some notation (since Maple has no 'big star' free for a usual notation:

```
> 'Conv(f,g)' = `f#g`;
```

$$\text{Conv}(f, g) = f \# g$$

Remember the Convolution Theorem, there are 2 versions: a general one and one for the Fourier transform (statements may vary by a constant factor depending on conventions used for the Fourier transform):

```
> # Convolution Theorem, general version
```

```
# Reference ???;
```

```
http://web.eecs.utk.edu/~roberts/WebAppendices/D-ConvProperties.pdf
```

```
"area of the convolution = product of the areas";
```

```
'Int( Conv(f,g)(t), t = -infinity .. infinity) =  
  Int(f(t), t = -infinity .. infinity) * Int( g(t), t = -infinity ..  
  infinity)';
```

```
'Int( `(f#g)`(t), t = -infinity .. infinity) =  
  Int(f(t), t = -infinity .. infinity) * Int( g(t), t = -infinity ..  
  infinity)';
```

"area of the convolution = product of the areas"

$$\int_{-\infty}^{\infty} \text{Conv}(f, g)(t) dt = \int_{-\infty}^{\infty} f(t) dt \int_{-\infty}^{\infty} g(t) dt$$

$$\int_{-\infty}^{\infty} (f \# g)(t) dt = \int_{-\infty}^{\infty} f(t) dt \int_{-\infty}^{\infty} g(t) dt$$

```
> # Convolution Theorem, version for Fourier transforms
```

```
'Phi( Conv(f,g) ) = Phi(f)* Phi(g)';
```

```
Phi( `f#g` ) = Phi(f)*Phi(g);
```

$$\Phi(\text{Conv}(f, g)) = \Phi(f) \Phi(g)$$

$$\Phi(f \# g) = \Phi(f) \Phi(g)$$

As corollaries the convolution can be expressed by the Fourier transform and any convolution product commutes with the Fourier transform

```
> # Corollary: convolution computed via Fourier transforms
```

```
`f#g` = (Phi@@(-1))( Phi(f)*Phi(g) );
```

```
#`` = (Phi@@(-1))( F*G ); ``; F=Phi(f), G=Phi(g), Phi = `Fourier  
transform`;
```

$$f \# g = (\Phi^{(-1)})(\Phi(f) \Phi(g))$$

```
> # Corollary: iterated convolution products
```

```
Phi( `f#g#h ...` ) = Phi(f)*Phi(g)*Phi(h)*` ...`;
```

```
#Phi(f) = 'sinc(x*a(k))', `...`;
```

$$\Phi(f \# g \# h \dots) = \Phi(f) \Phi(g) \Phi(h) \dots$$

Proofs

```
> # Maple knows the identity:
```

```
fourier(f(t), t, z)*fourier(g(t), t, z):
```

```
'invfourier'(% , z, t);
```

```
`=`subs(int=Int, %): subs(_U1 = eta, %):
```

```
combine(%);
```

```
Change(% , eta=-y, y);
```

```
`=`'Conv'(g, f )(t);
```

```
#``=`(g#f)(t)`;
```

$$\text{invfourier}(\text{fourier}(f(t), t, z) \text{fourier}(g(t), t, z), z, t)$$

$$= \int_{-\infty}^{\infty} f(-\eta) g(t + \eta) d\eta$$

$$= \int_{-\infty}^{\infty} f(y) g(t - y) dy$$

$$= \text{Conv}(g, f)(t)$$

```
> `(f#g) # h`;
```

```
`=`(Phi@@(-1))( Phi( `f#g` ) * Phi(h) );
```

```
`=`(Phi@@(-1))( (Phi(f)*Phi(g)) * Phi(h) );
```

$$(f \# g) \# h$$

$$= (\Phi^{(-1)})(\Phi(f \# g) \Phi(h))$$

$$= (\Phi^{(-1)})(\Phi(f) \Phi(g) \Phi(h))$$

Convolutions for Rectangles

The convolution of 2 rectangles can be described completely

```
> # k = 0 and 1
```

```
'Trapez' = `( s(0, . ) # s(1, . ) )`(t);
```

```
exampleData:={a1=-1, b1=1, h1=1/2, # s(0,t);
```

```
a2=-1/2, b2=1/2, h2=1}; # s(1,t);
```

```
Trapez = ( s(0, . ) # s(1, . ) )(t)
```

$$\text{exampleData} := \{a1 = -1, a2 = -\frac{1}{2}, b1 = 1, b2 = \frac{1}{2}, h1 = \frac{1}{2}, h2 = 1\}$$

```
> Trapez:='Conv'( t -> s(0,t), t -> s(1, t) )(t);
```

```
Trapez:=value(%);
```

```
plot(Trapez, t=-2 .. 2, thickness=2, color=black):
```

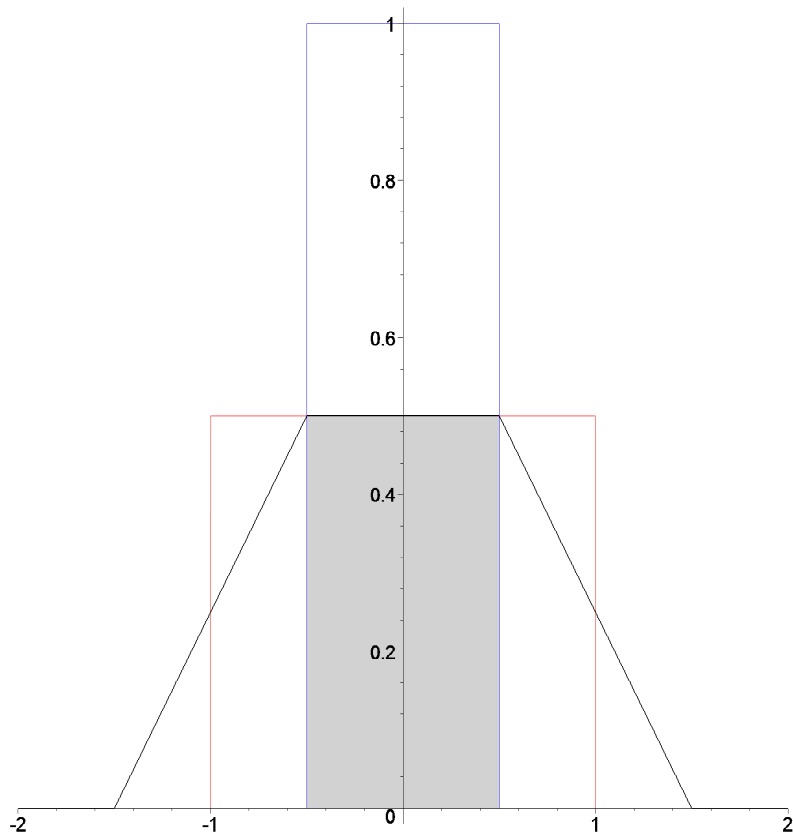
```
plot([s(0,t), s(1,t)], t=-2 .. 2, color=[red, blue]):
```

```
plottools:-rectangle([-1/2,0], [1/2,1/2], color="LightGrey");
```

```
plots:-display(%%%, %%, %);
```

$$\text{Trapez} := \text{Conv}(t \rightarrow s(0, t), t \rightarrow s(1, t))(t)$$

$$\text{Trapez} := \begin{cases} 0 & t < -\frac{3}{2} \\ \frac{3}{4} + \frac{t}{2} & t < -\frac{1}{2} \\ \frac{1}{2} & t < \frac{1}{2} \\ \frac{3}{4} - \frac{t}{2} & t < \frac{3}{2} \\ 0 & \frac{3}{2} \leq t \end{cases}$$



```
> `Convolution = Trapez = Wing + Torso and extending by Zero`;
`Torso := constant values within the support, Wings := the difference`;

Convolution = Trapez = Wing + Torso and extending by Zero
Torso := constant values within the support, Wings := the difference
```

Let us view at it as something with a rectangle as a 'torso' and the remaining wings, which helps to study iterated convolution products

```
> [`Support of convolution`, `starting` = a1+a2 , `ending`=b1+b2];
eval(% , exampleData);

[Support of convolution, starting = a1 + a2, ending = b1 + b2]
[Support of convolution, starting = -3/2, ending = 3/2]
```

This holds for any convolution of functions living on intervals [a1 ... b1] and [a2... b2] (use the definition of a convolution, perhaps in any book).

The next is for rectangles only (I have no citation and what I have seen is without 'min' and 'max', which would make it false in non-symmetric situation). And in our situation of symmetric and "shrinking

rectangles" the formula becomes simple:

```
> # holds for rectangles
[Torso, `starting` = min(b1+a2, a1+b2) , `ending`=max(b1+a2, a1+b2)];
eval(% , [a1=-b1,a2=-b2]) assuming b2 < b1;
eval(% , exampleData);

[Torso, starting = min(a1 + b2, b1 + a2), ending = max(a1 + b2, b1 + a2)]
[Torso, starting = -b1 + b2, ending = b1 - b2]
[Torso, starting = -1/2, ending = 1/2]
```

Thus one need the height of the torso for a complete description. That follows through the area of the Trapezoid and due to the Convolution Theorem that is the product of the areas of the 2 according rectangles.

```
> # area of trapez = height * average of bottom and top
area = height* (`length bottom`+`length top`)/2;
isolate(% , height): simplify(%);
`=rhs(%):
eval(% , area= 1);
eval(% , `length bottom` = 2* 3/2); # look at the result for 'Trapez'
eval(% , `length top` = 2* 1/2); # look at the result for 'Trapez'
```

$$\begin{aligned} \text{area} &= \frac{\text{height} (\text{length bottom} + \text{length top})}{2} \\ \text{height} &= \frac{2 \text{ area}}{\text{length bottom} + \text{length top}} \\ &= \frac{2}{\text{length bottom} + \text{length top}} \\ &= \frac{2}{3 + \text{length top}} \\ &= \frac{1}{2} \end{aligned}$$

```
> `height` = 2*area/(abs(-b1-b2+a1+a2)+abs(a1+b2-b1-a2));
`=rhs(%):
eval(% , [a1=-b1, a2=-b2]): simplify(%); # symmetric w.r.t. 0
eval(% , area= 1);
eval(% , exampleData);
```

$$\begin{aligned} \text{height} &= \frac{2 \text{ area}}{|-b1 - b2 + a1 + a2| + |-b1 - a2 + a1 + b2|} \\ &= \frac{\text{area}}{|b1 + b2| + |b1 - b2|} \\ &= \frac{1}{|b1 + b2| + |b1 - b2|} \\ &= \frac{1}{2} \end{aligned}$$

It was used, that in our example the areas equal 1, thus we got: the height equal 1/2. In any case.

```
> Int(`(f#g)`(t), t= -infinity .. infinity) =
Int(f(t), t= -infinity .. infinity)*Int(g(t), t= -infinity ..
infinity);
`;
`Int(s(k,t), t= -infinity .. infinity)`: '%' = simplify( value(% ) );
```

$$\int_{-\infty}^{\infty} (f \# g)(t) dt = \int_{-\infty}^{\infty} f(t) dt \int_{-\infty}^{\infty} g(t) dt$$

$$\int_{-\infty}^{\infty} s(k, t) dt = 1$$

[>

Iterated convolution of those rectangles

Define (by recursion) an iterated convolution product

```
> 'S'(n,t) = `#`('s'(j,t), j=0..n);
` `;
S:=proc(n)
option remember;
local fct;
fct:= unapply(thisproc(n-1), t);
Conv(fct, 'x -> s(n,x)')(t); #return(%);
#subs(Int = int, %)(t);
value(%); # assuming n::nonnegint;
simplify(%); # assuming n::nonnegint;
end proc;
S(0):=s(0,t):
```

$$S(n, t) = \#(s(j, t), j = 0 \dots n)$$

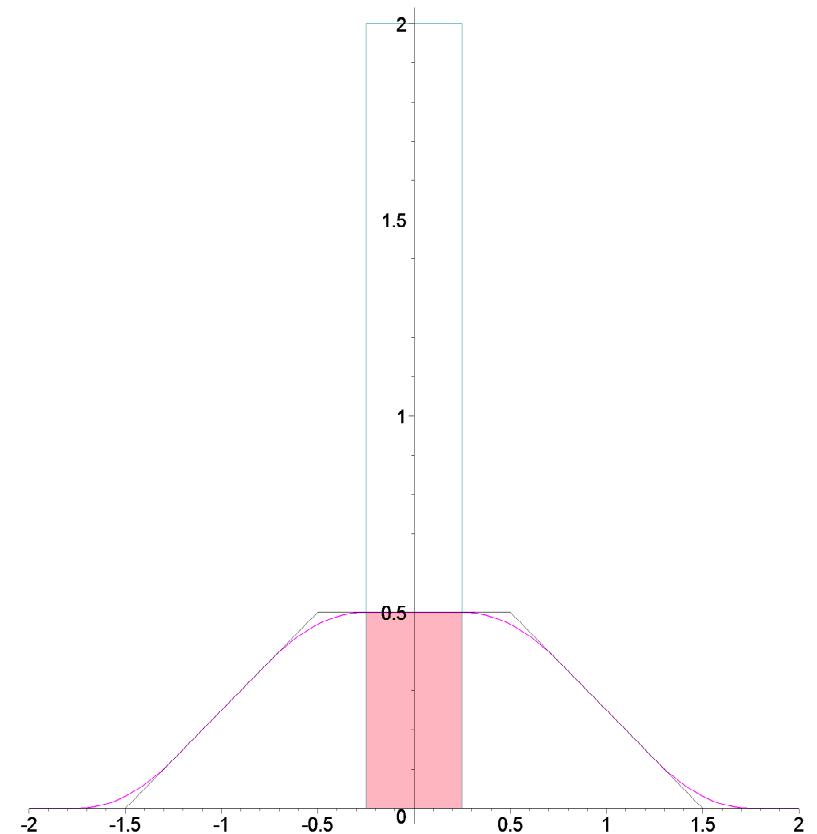
```
S:=proc(n)
local fct;
option remember;
fct:= unapply(thisproc(n-1), t); Conv(fct, 'x -> s(n,x)')(t); value(%); simplify(%)
end proc
```

Now - as in the example - decompose into wings and a torso (= the 'center', a rectangle)

```
> 'S'(n,t) = Wing(n,t) + Torso(n,t);
` ` = LeftWing(n,t) + Torso(n,t) + RightWing(n,t);
LeftWing(n,t) = RightWing(n,-t);

S(n,t) = Wing(n,t) + Torso(n,t)
= LeftWing(n,t) + Torso(n,t) + RightWing(n,t)
LeftWing(n,t) = RightWing(n,-t)

> theRange:= -2 .. 2:
#p01:=plot([s(0,t), s(1,t)], t=theRange, color=[red, blue,
"DarkMagenta"]);
pS1:= plot([S(1), s(2,t)], t=theRange, color=[black, "DarkCyan"],
tickmarks=[8, 4]):
pS2:= plot(S(2), t=theRange, thickness=2, color=magenta):
#pT1:= plot(s(1,t)/2, t=-1/2 .. 1/2, filled=[color="wheat",
transparency=0.1]):
#pT2:= plot(s(2,t)/4, t=-1/4 .. 1/4, filled=[color="LightPink",
transparency=0.9]):
pT2:=plottools:-rectangle([-2^(-2),0], [2^(-2),1/2], color="LightPink"):
plots:-display( pS1,pS2,pT2);
```



The pink curve is the convolution of the trapez (= 2-fold rectangles) with the next rectangle (the small one reaching the value 2) and the torso of this 3-fold convolution is the inner rectangle, given in pink and having height = 1/2 as well.

After studying some iterations (say 3 or 4) one can set up the following assertions about the wings and the torse (check for k=2, the above plot)

```
> Support(RightWing(k,t)) = 2^(-k) .. Sum(2^(-j), j=0 .. k); value(%);
eval(% , k=2), k=2;
```

$$\text{Support}(\text{RightWing}(k, t)) = 2^{(-k)} \dots \left(\sum_{j=0}^k 2^{(-j)} \right)$$

$$\text{Support}(\text{RightWing}(k, t)) = 2^{(-k)} \dots -2^{(-k)} + 2$$

$$\text{Support}(\text{RightWing}(2, t)) = \frac{1}{4} \dots \frac{7}{4}, k = 2$$

```
> Torso(k,t) = 's(k+1,t)/2^(k+1)';
` `=simplify(rhs(%)) assuming n::posint;
` `= 1/2 * 'rect'(2^(-k-1), 2^(-k-1), t);
eval(% , k=2), k=2;
```

$$\begin{aligned}\text{Torso}(k, t) &= \frac{s(k+1, t)}{2^{(k+1)}} \\ &= \frac{1}{2} \left\{ \begin{array}{ll} 1 & -2^{(-k-1)} \leq t \text{ and } t \leq 2^{(-k-1)} \\ 0 & \text{otherwise} \end{array} \right\} \\ &= \frac{1}{2} \text{rect}(2^{(-k-1)}, 2^{(-k-1)}, t) \\ &= \frac{1}{2} \left\{ \begin{array}{ll} 1 & \frac{1}{8} \leq t \text{ and } t \leq \frac{1}{8} \\ 0 & \text{otherwise} \end{array} \right\}, k=2\end{aligned}$$

Do some check at least for low values (the procedure is *very* slow)

```
> N:=4;

'S(N) = 1/2*rect(-2^(-N), 2^(-N),t)'; %:
simplify(%) assuming -2^(-N) <= t, t < 2^(-N):

is(%, `assuming ( -2^(-N) <= t, t < 2^(-N) )`);
#plot(%, t = -2^(-N+1/8) .. 2^(-N+1/8));

N:=4
S(N)=1/2 rect(-2^(-N), 2^(-N), t)

true, assuming ( -2^(-N) <= t, t < 2^(-N) )
```

— Ingredience for a proof

One uses the formulae about the supports already used in the example above

```
> `RightWing # s(k+1,t)`;
[ `Support`(`RightWing # s(k+1,t)`), `starting` =a1+a2 ,
`ending`=b1+b2];
eval(%, [a1=2^(-k), b1 = 2 - 2^(-k), a2=-2^(-k-1), b2 = 2^(-k-1)]):
simplify(%)
#eval(%, k=N);

RightWing # s(k+1,t)
[ Support(RightWing # s(k+1,t)), starting = a1 + a2, ending = b1 + b2 ]

[ Support(RightWing # s(k+1,t)), starting = 2^(-k-1), ending = -2^(-k-1) + 2 ]
> `Torso # s(k+1,t)`;
[ `Support`(`Torso # s(k+1,t)`), `starting` =a1+a2 , `ending`=b1+b2];
eval(%, [a1=-2^(-k), b1 = 2^(-k), a2=-2^(-k-1), b2 = 2^(-k-1)]):
simplify(%)
#eval(%, k=N);

Torso # s(k+1,t)
[ Support(Torso # s(k+1,t)), starting = a1 + a2, ending = b1 + b2 ]

[ Support(Torso # s(k+1,t)), starting = -3 2^(-k-1), ending = 3 2^(-k-1) ]
> `Torso # s(k+1,t)`;
[ `new Torso`=`Torso`(`Torso # s(k+1,t)`), `starting` = min(b1+a2,
a1+b2) , `ending`=max(b1+a2, a1+b2)];
eval(%, [a1=-2^(-k), b1 = 2^(-k), a2=-2^(-k-1), b2 = 2^(-k-1)]):
simplify(%)
#eval(%, k=N);
#'N': '%='%;

Torso # s(k+1,t)
[new Torso = Torso(Torso # s(k+1,t)), starting = min(a1 + b2, b1 + a2),
```

ending = max(a1 + b2, b1 + a2)]

```
[ new Torso = Torso(Torso # s(k+1,t)), starting = -2^(-k-1), ending = 2^(-k-1) ]
> `height of new Torso`;
`area of old torso` = `width*height`, width = 2*2^(-k), height = 1/2;
`=2^(-k);
`area of s(k+1,t)` = 1;
`area of new torso` = `product of both`;
`=2^(-k);
`;
`height` = 2*area/(abs(-b1-b2+a1+a2)+abs(a1+b2-b1-a2));
`=rhs(%)
eval(%, [a1=-2^(-k), b1 = 2^(-k), a2=-2^(-k-1), b2 = 2^(-k-1)]):
simplify(%)
eval(%, area = 2^(-k)): simplify(%)
#eval(%, k=N);
```

$$\begin{aligned}\text{height of new Torso} \\ \text{area of old torso} &= \text{width} * \text{height}, \text{width} = 2 \cdot 2^{(-k)}, \text{height} = \frac{1}{2} \\ &= 2^{(-k)} \\ \text{area of } s(k+1, t) &= 1 \\ \text{area of new torso} &= \text{product of both} \\ &= 2^{(-k)} \\ \text{height} &= \frac{2 \text{ area}}{|-b1 - b2 + a1 + a2| + |-b1 - a2 + a1 + b2|} \\ &= 2^{(k-1)} \text{ area} \\ &= \frac{1}{2}\end{aligned}$$

From that one "sees", that a recursive proof can be made, since the according ranges fir and do not intersect. I have to admit, that I am too lazy to write it down (better using paper + pencil the handling Maple).

Now multiplying with the next rectangle reduces to the range of that rectangle, as it it shrinked by a factor (and only the height changes).

Thus one has: $S(k) s(k+1, t) = \frac{1 s(k+1, t)}{2}$

```
> 'S(k)*s(k+1,t) = s(k+1,t)/2';
#N:=3; #N:=5;
'S(N)*s(N+1,t) = s(N+1,t)/2'; simplify(%); is(%)

S(k) s(k+1, t) = 1/2 s(k+1, t)

S(N) s(N+1, t) = 1/2 s(N+1, t)
```

$$\begin{cases} 0 & t < \frac{-1}{16} \\ 4 & t \leq \frac{1}{16} \\ 0 & \frac{1}{16} < t \end{cases} = \begin{cases} 0 & t < \frac{-1}{16} \\ 4 & t \leq \frac{1}{16} \\ 0 & \frac{1}{16} < t \end{cases}$$

true

[>

Bring it together

```
[ >
> u[k] = 'sinc(t*a(k))', s[k] = 's'(k,t);
>
Int( Product(u[k], k=0..n) * u[n+1], t = IR .. ``);
``=Int( Product(Phi(s[k]), k=0..n) * u[n+1], t = IR .. ``);
``=Int(Phi((`#`)(s[k]), k=0..n) * u[n+1], t = IR .. ``); # by convolution
theorem
#Phi((`#`)(s[k]), k=0..n);
u_k = sinc(t a(k)), s_k = s(k, t)
```

$$\begin{aligned} & \int_{\mathbb{R}} u_{n+1} \left(\prod_{k=0}^n u_k \right) dt \\ &= \int_{\mathbb{R}} \left(\prod_{k=0}^n \Phi(s_k) \right) u_{n+1} dt \\ &= \int_{\mathbb{R}} \Phi(\#(s_k), k=0..n) u_{n+1} dt \end{aligned}$$

Now use the Plancherel-Parseval formula to continue (no conjugation need in our case)

```
[ > ``=Int(Phi( Phi((`#`)(s[k]), k=0..n) ) * Phi(u[n+1]), t = IR .. ``);
``=Int(Phi( Phi((`#`)(s[k]), k=0..n) ) * s[n+1], t = IR .. ``);

= \int_{\mathbb{R}} \Phi(\Phi(\#(s_k), k=0..n)) \Phi(u_{n+1}) dt

= \int_{\mathbb{R}} \Phi(\Phi(\#(s_k), k=0..n)) s_{n+1} dt
```

But $\Phi^2 = -2\pi \text{id}$ and the iterated product is symmetric w.r.t. zero (follows from above assertion), so the Minus sign drops out and that is

```
[ > ``=Int(2*Pi*(((`#`)(s[k]), k=0..n) ) * s[n+1], t = IR .. ``);
``='Int(2*Pi*S(n,t) * s(n+1,t), t = IR .. ``)';
``='Int(2*Pi*s(n+1,t)/2, t = IR .. ``)';
``='Int(2*Pi*s(n+1,t)/2, t = -infinity .. infinity)';
```

value(%) assuming n::nonnegint: combine(%);

$$\begin{aligned} &= \int_{\mathbb{R}} 2\pi (\#(s_k), k=0..n) s_{n+1} dt \\ &= \int_{\mathbb{R}} 2\pi S(n, t) s(n+1, t) dt \\ &= \int_{\mathbb{R}} \pi s(n+1, t) dt \\ &= \int_{-\infty}^{\infty} \pi s(n+1, t) dt \\ &= \pi \end{aligned}$$

[>

Appendix: formula for the torso

Show that Torso starts at $\min(b_1+a_2, a_1+b_2)$ and ends at $\max(b_1+a_2, a_1+b_2)$ or likewise, that differentiating the convolution w.r.t. t is zero on that interval

```
[ > `f#g` = (Phi@@(-1))( Phi(f)*Phi(g) );
f#g=(Phi^(-1))(Phi(f)Phi(g))
> diff(invfourier(F(x), x,t), t) = 'invfourier'(F(x)*x*I, x,t); #convert(%,
is(%);

\frac{\partial}{\partial t} \text{invfourier}(F(x), x, t) = \text{invfourier}(F(x) x I, x, t)

true

> theAssumptions:=
a1 < b1, a2 < b2, # general assumption for rectangles
a1+a2 < t, t < b1+b2; # support of the convolution
theAssumptions := a1 < b1, a2 < b2, a1 + a2 < t, t < b1 + b2

> diffConv:=Diff( `(f#g)`)(t), t);

'fourier(rect(a1,b1,t),t,x)*fourier(rect(a2,b2,t),t,x)':
``='invfourier(%*x*I, x,t)'; # = differentiation
% assuming a1 < b1, a2 < b2;

subsindets(%, 'Heaviside( anything )', 'u -> convert(u, piecewise,t)');
# rewrite as piecewise

simplify(%) assuming (theAssumptions);

diffConv:=rhs(%):

diffConv := \frac{d}{dt} (f#g)(t)

= invfourier( fourier(rect(a1, b1, t), t, x) fourier(rect(a2, b2, t), t, x) x I, x, t)

= -Heaviside(-t + a1 + a2) + Heaviside(-t + a1 + b2) + Heaviside(-t + b1 + a2) - Heaviside(-t + b1 + b2)

= -\begin{pmatrix} 1 & t \leq a1 + a2 \\ 0 & a1 + a2 < t \end{pmatrix} + \begin{pmatrix} 1 & t \leq a1 + b2 \\ 0 & a1 + b2 < t \end{pmatrix} + \begin{pmatrix} 1 & t \leq b1 + a2 \\ 0 & b1 + a2 < t \end{pmatrix} - \begin{pmatrix} 1 & t \leq b1 + b2 \\ 0 & b1 + b2 < t \end{pmatrix}
```

$$= -1 + \begin{pmatrix} 1 & t \leq a1 + b2 \\ 0 & a1 + b2 < t \end{pmatrix} + \begin{pmatrix} 1 & t \leq b1 + a2 \\ 0 & b1 + a2 < t \end{pmatrix}$$

[Now help Maple ...

```
> theCondition:=[min(b1+a2, a1+b2) < t, t < max(b1+a2, a1+b2)];
;;
'simplify(theCondition) assuming a1+b2 <= b1+a2'; # case 1, a1+b2 =
minimum
Case1:= op(%);
'simplify(theCondition) assuming b1+a2 <= a1+b2'; # case 2, b1+a2 =
minimum
Case2:= op(%);
theCondition := [ min(a1 + b2, b1 + a2) < t, t < max(a1 + b2, b1 + a2)]

(simplify(theCondition) assuming (a1 + b2 ≤ b1 + a2))
Case1 := a1 + b2 < t, t < b1 + a2
(simplify(theCondition) assuming (b1 + a2 ≤ a1 + b2))
Case2 := b1 + a2 < t, t < a1 + b2
```

```
> # case 1: a1+b2 <= b1+a2
simplify(diffConv) assuming Case1;
simplify(diffConv) assuming Case2;
```

0

0

[>